

FIG. 1

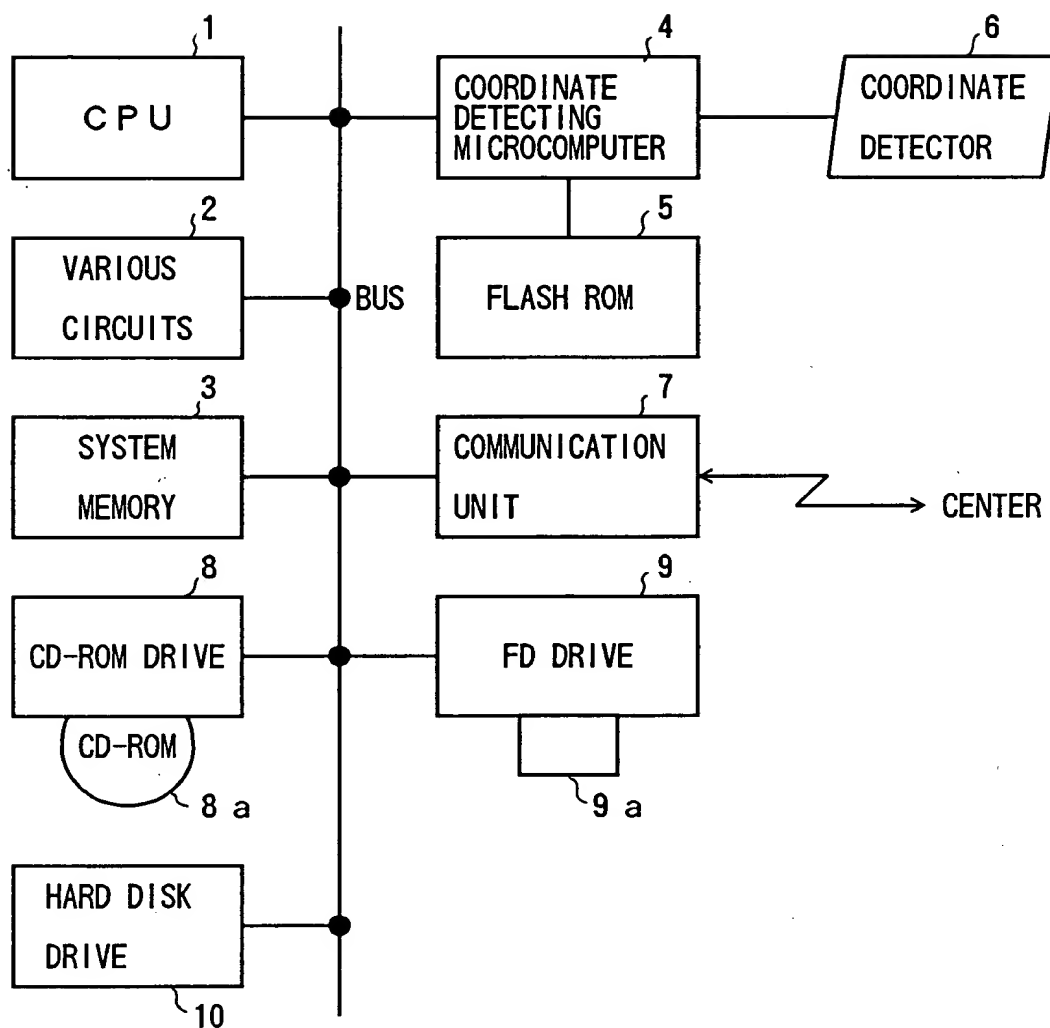


FIG. 2

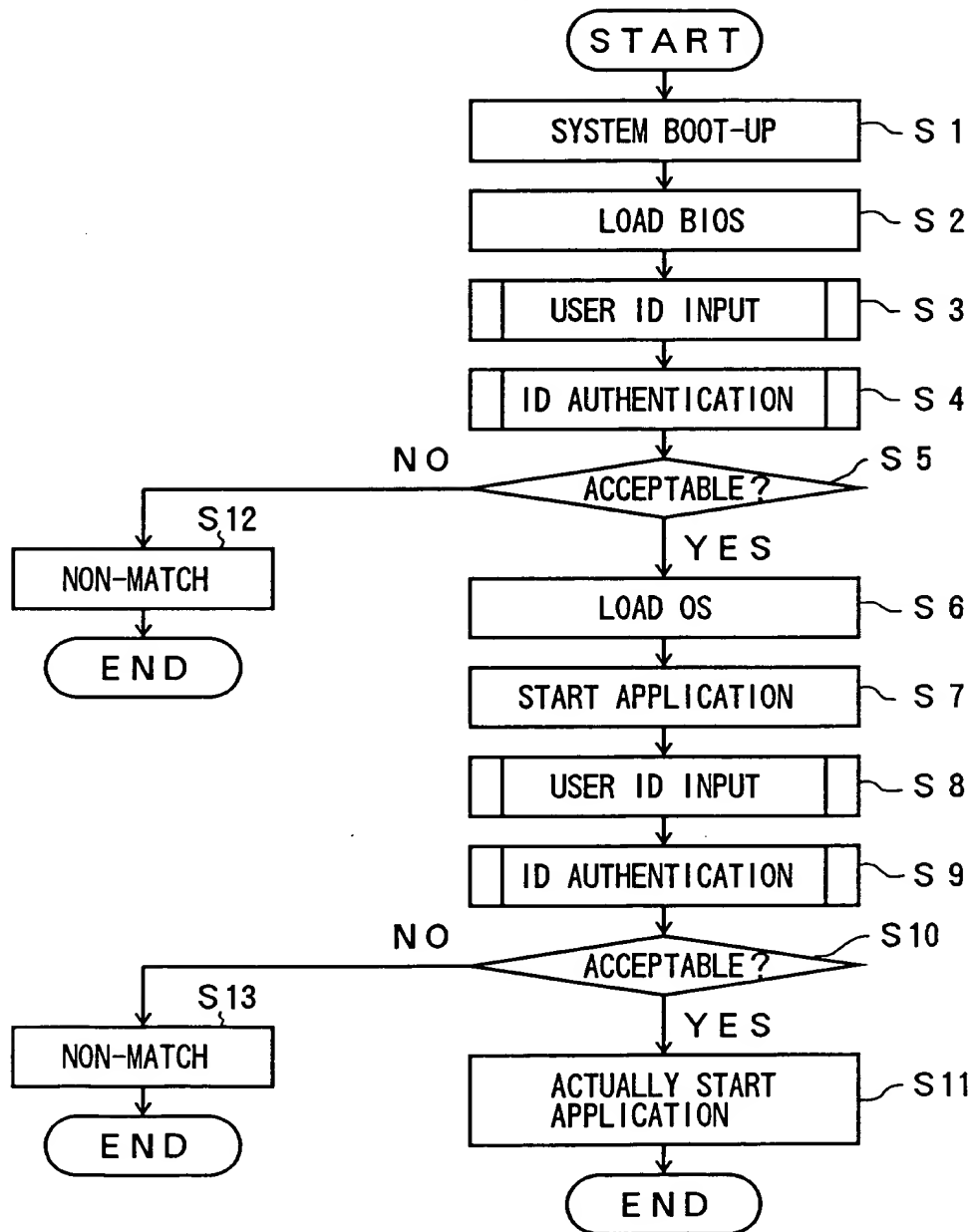


FIG. 2

FIG. 3

SOFTWARE OF CPU 1

COORDINATE DETECTING
MICROCOMPUTER 4

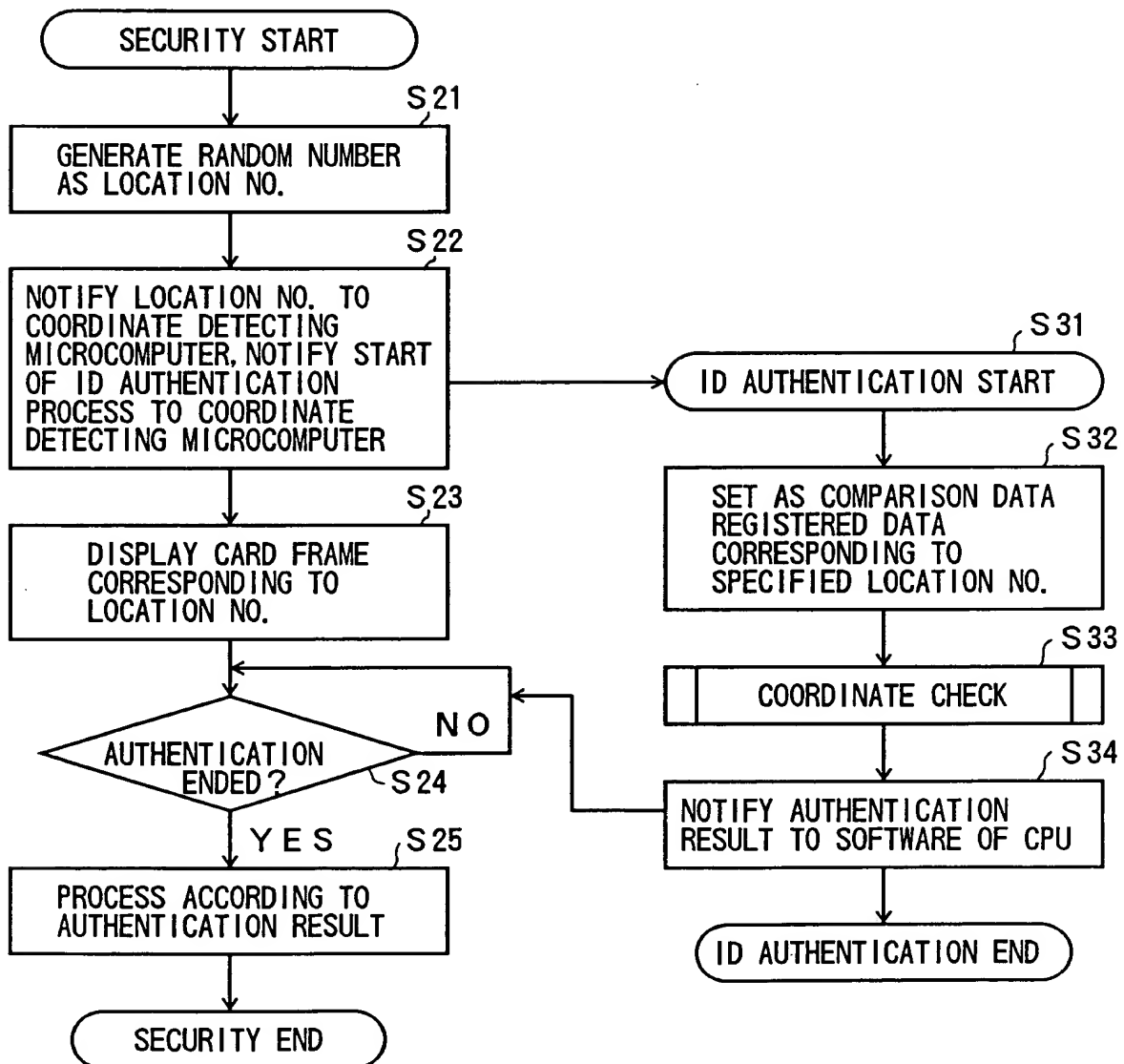
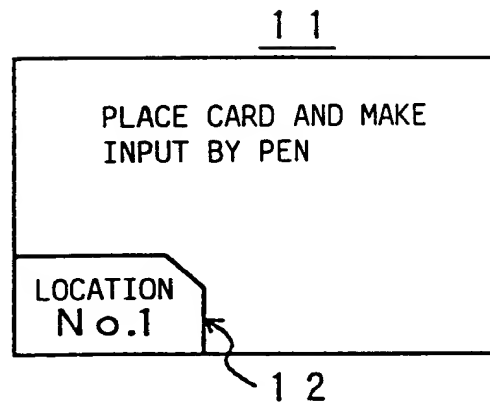


FIG. 3

FIG. 4



10340-625600

FIG. 5A

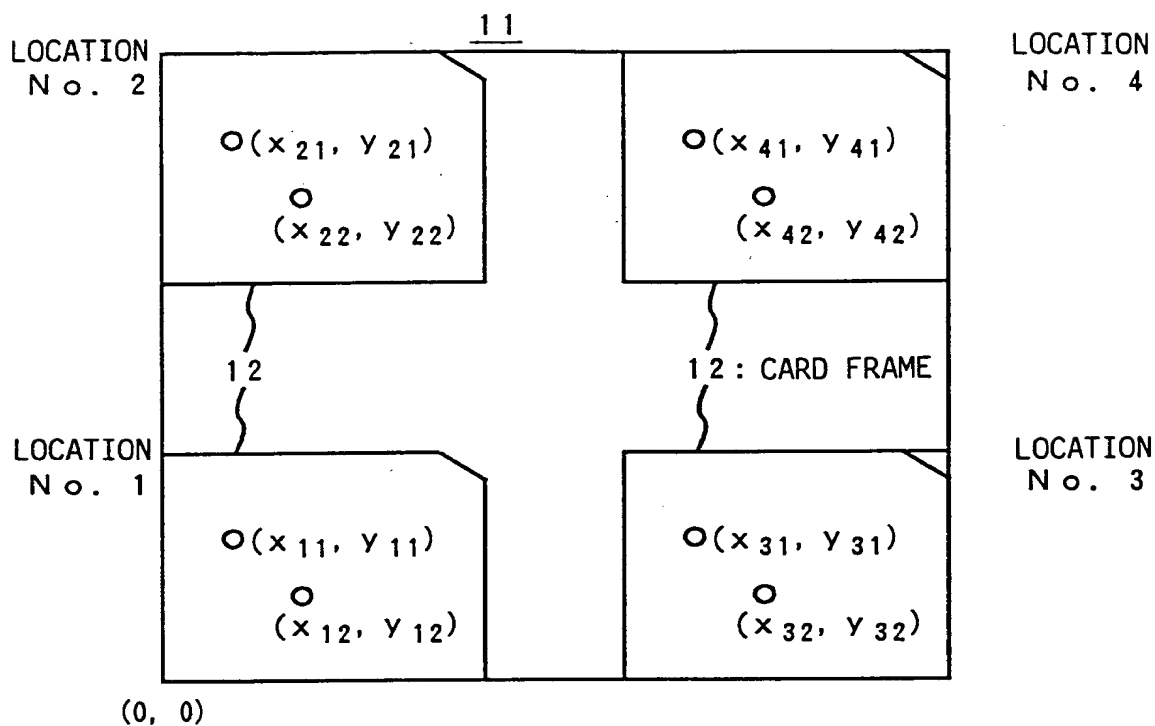


FIG. 5B

LOCATION No.	POINT No.	COORDINATE
1	1	(x_{11}, y_{11})
	2	(x_{12}, y_{12})
2	1	(x_{21}, y_{21})
	2	(x_{22}, y_{22})
3	1	(x_{31}, y_{31})
	2	(x_{32}, y_{32})
4	1	(x_{41}, y_{41})
	2	(x_{42}, y_{42})

TOP SECRET

FIG. 6A

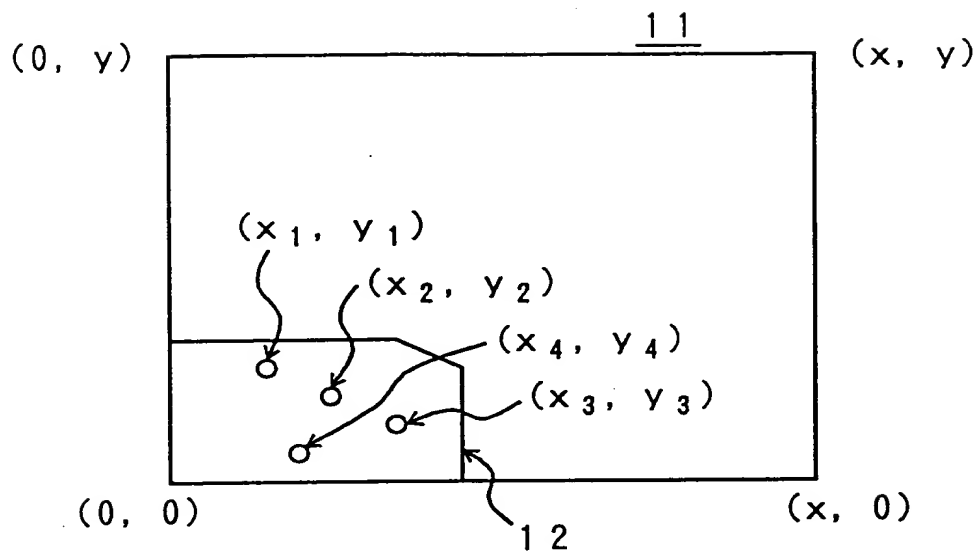


FIG. 6B

No.	COORDINATE
1	(x_1, y_1)
2	(x_2, y_2)
3	(x_3, y_3)
4	(x_4, y_4)

FIG. 7

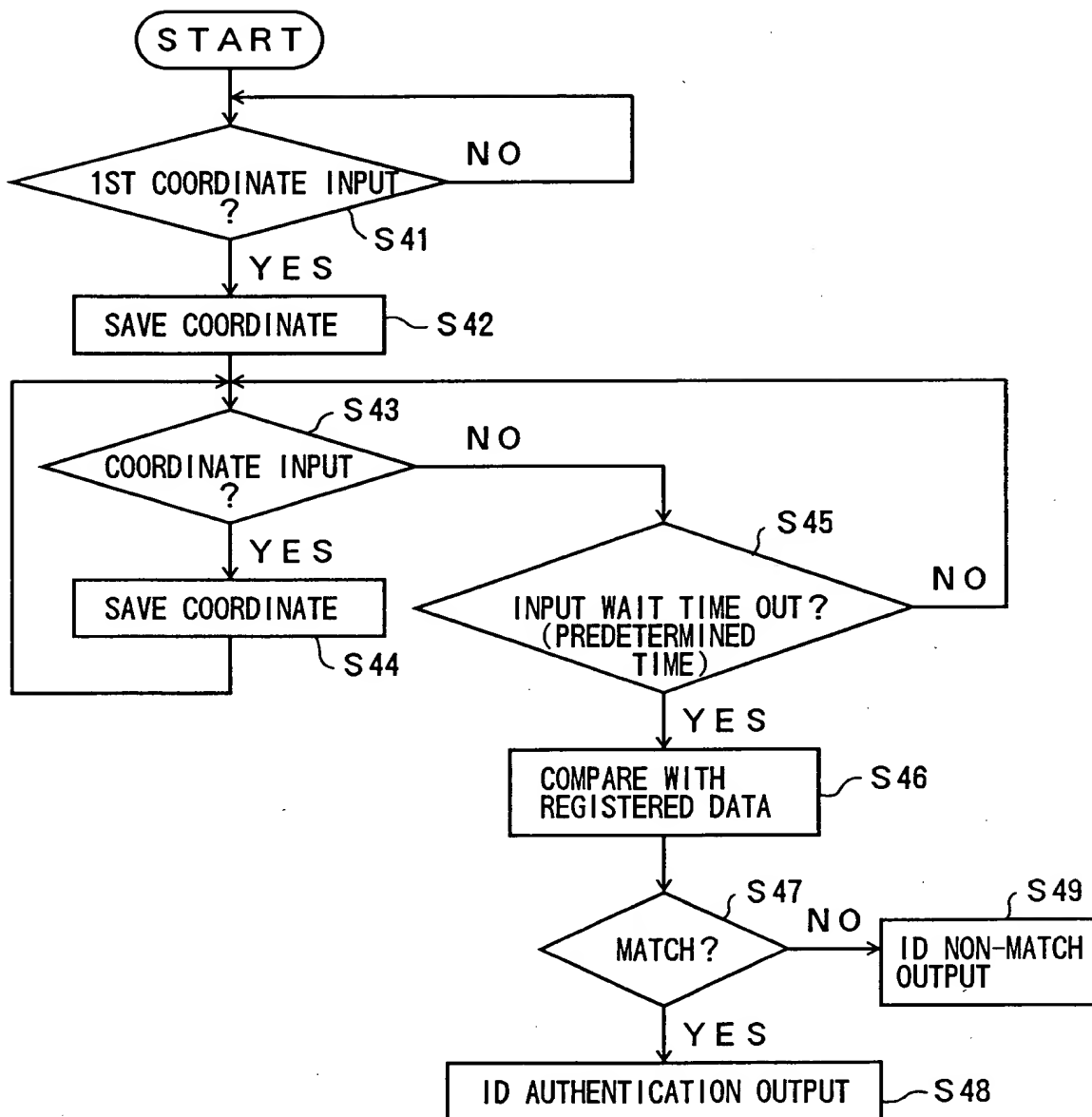


FIG. 8

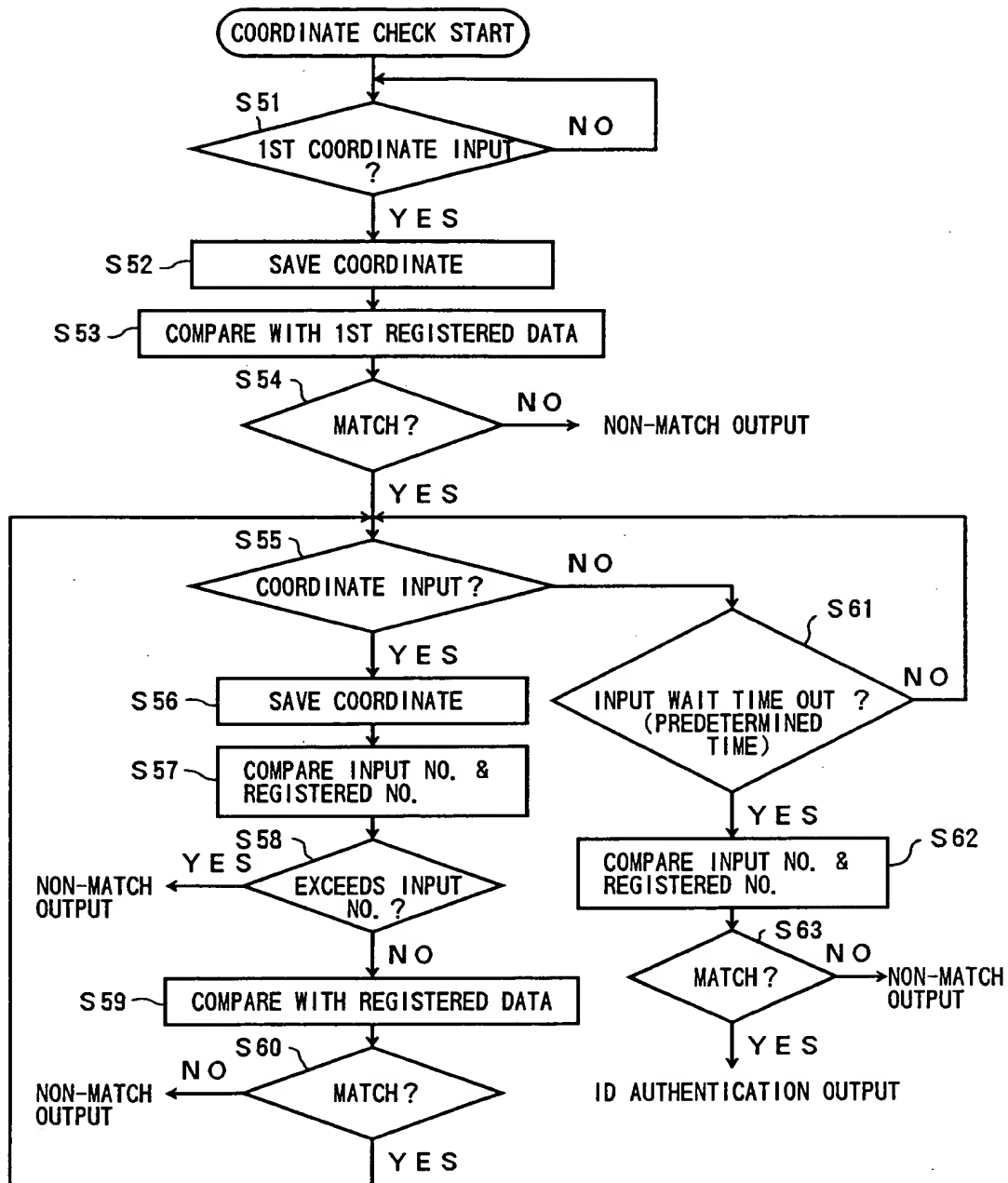


FIG. 9

SOFTWARE OF CPU 1

COORDINATE DETECTING
MICROCOMPUTER 4

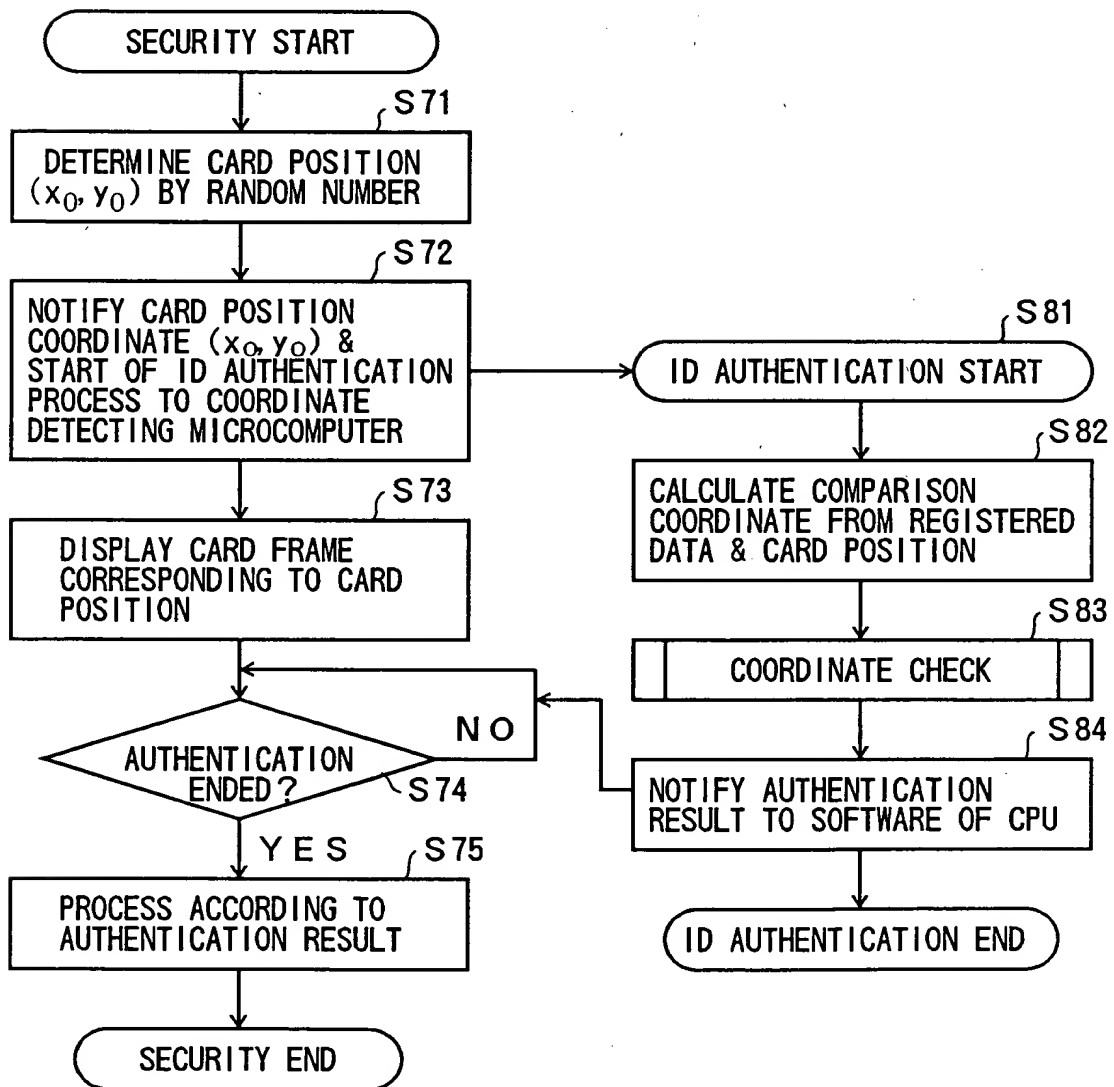


FIG. 9

FIG. 10A

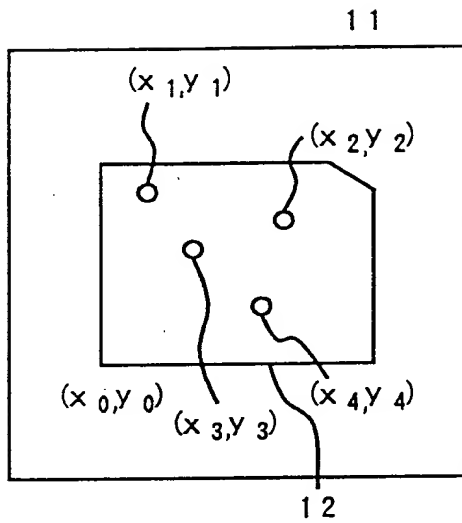


FIG. 10B

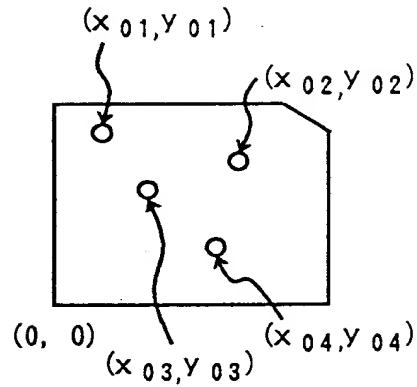


FIG. 10C

POINT No.	CARD ORIGIN	HOLE COORDINATE VALUE WITHIN CARD	COMPARISON COORDINATE
1	(x_0, y_0)	(x_{01}, y_{01})	$(x_1, y_1) = (x_0 + x_{01}, y_0 + y_{01})$
2		(x_{02}, y_{02})	$(x_2, y_2) = (x_0 + x_{02}, y_0 + y_{02})$
3		(x_{03}, y_{03})	$(x_3, y_3) = (x_0 + x_{03}, y_0 + y_{03})$
4		(x_{04}, y_{04})	$(x_4, y_4) = (x_0 + x_{04}, y_0 + y_{04})$

↑
REGISTERED DATA

↑
DATA RECEIVED FROM CPU

↑
OBTAIN DATA FOR COMPARISON WITH
ACTUALLY DETECTED COORDINATE
FOR AUTHENTICATION BY CALCULATION
PRIOR TO AUTHENTICATION

FIG. 11

SOFTWARE OF CPU 1

COORDINATE DETECTING MICROCOMPUTER 4

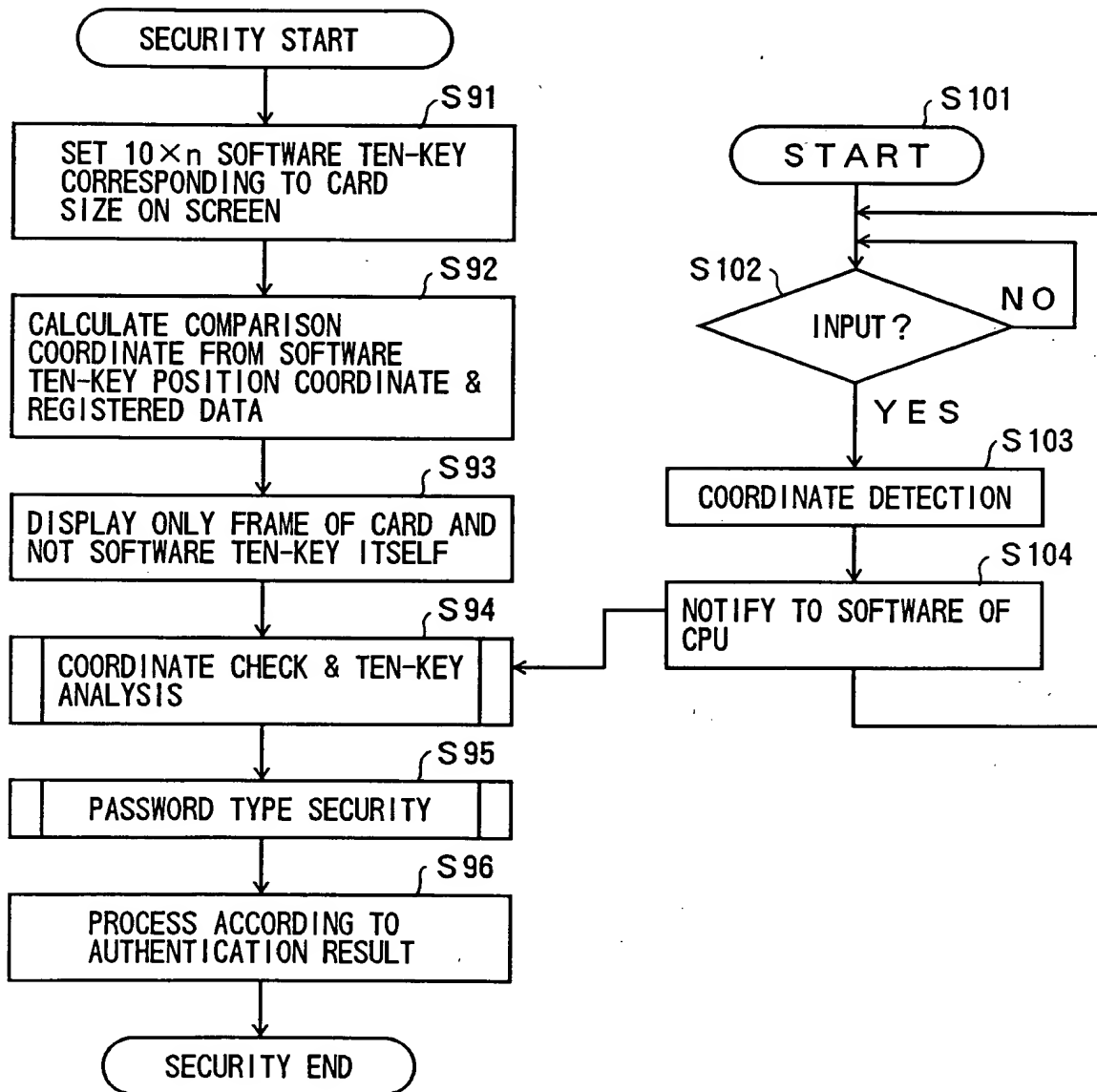
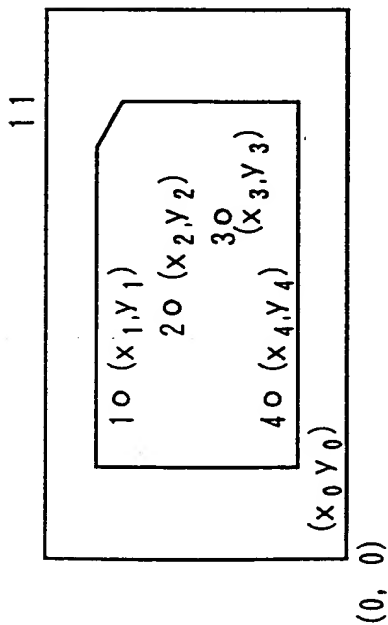


FIG. 12A



POINT	INPUT COORDINATE VALUE
1	(x_1, y_1)
2	(x_2, y_2)
3	(x_3, y_3)
4	(x_4, y_4)

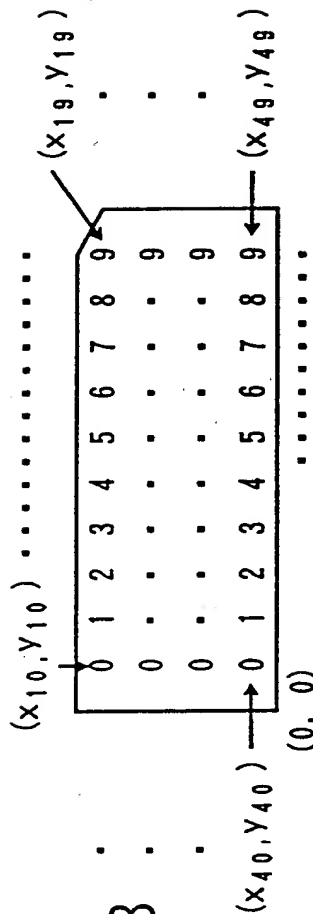


FIG. 12B

FIG. 12D

POINT No.	RECEIVED COORDINATE	ORIGIN COORDINATE OF SOFTWARE TEN-KEY	COMPARISON COORDINATE OF SOFTWARE TEN-KEY	COMPARISON RESULT	RESULT
1	(x_1, y_1)	(x_0, y_0)	$(x_1' - x_0, y_1 - y_0)$	(x_{12}, y_{12})	2
2	(x_2, y_2)		$(x_2' - x_0, y_2 - y_0)$	(x_{22}, y_{22})	6
3	(x_3, y_3)		$(x_3' - x_0, y_3 - y_0)$	(x_{32}, y_{32})	9
4	(x_4, y_4)		$(x_4' - x_0, y_4 - y_0)$	(x_{42}, y_{42})	2

COMPARE WITH $(x_{10}, y_{10}) \sim (x_{40}, y_{40})$ OUTPUT KEY CODE "2692"

FIG. 13A

POINT NO.	DETECTED COORDINATE FROM CPU	CARD ORIGIN COORDINATE FROM CPU	COMPARISON COORDINATE OF SOFTWARE TEN-KEY	COMPARISON RESULT
1	(x_1, y_1)	(x_0, y_0)	$(x_1' y_1') = (x_1 - x_0, y_1 - y_0)$	(x_{12}, y_{12})
2	(x_2, y_2)		$(x_2' y_2') = (x_2 - x_0, y_2 - y_0)$	(x_{26}, y_{26})
3	(x_3, y_3)		$(x_3' y_3') = (x_3 - x_0, y_3 - y_0)$	(x_{39}, y_{39})
4	(x_4, y_4)		$(x_4' y_4') = (x_4 - x_0, y_4 - y_0)$	(x_{42}, y_{42})

FIG. 13B

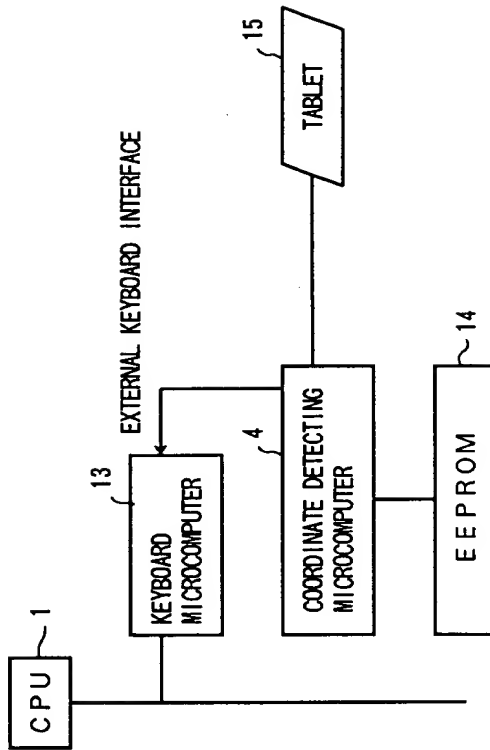


FIG. 14

SOFTWARE OF CPU 1

COORDINATE DETECTING
MICROCOMPUTER 4

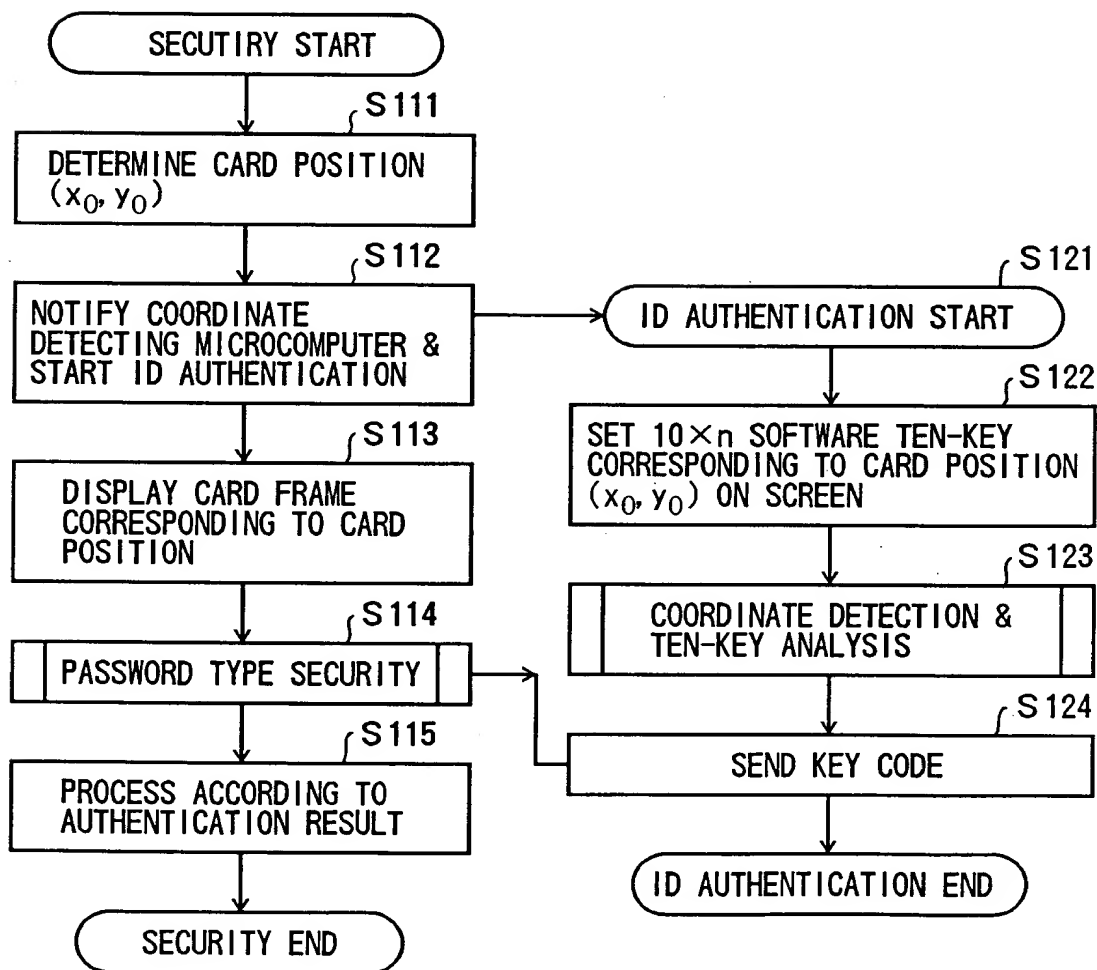


FIG. 15A

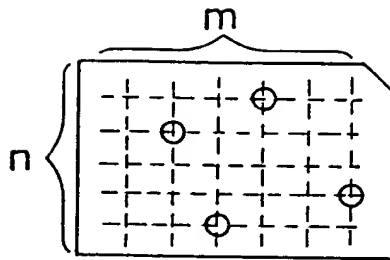


FIG. 15B

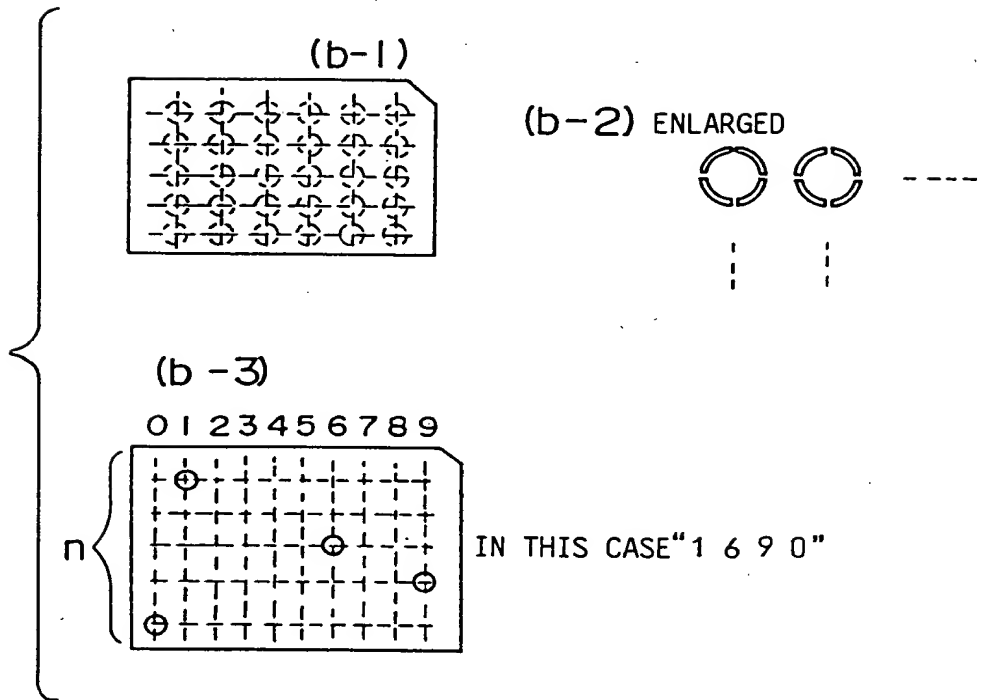


FIG. 16

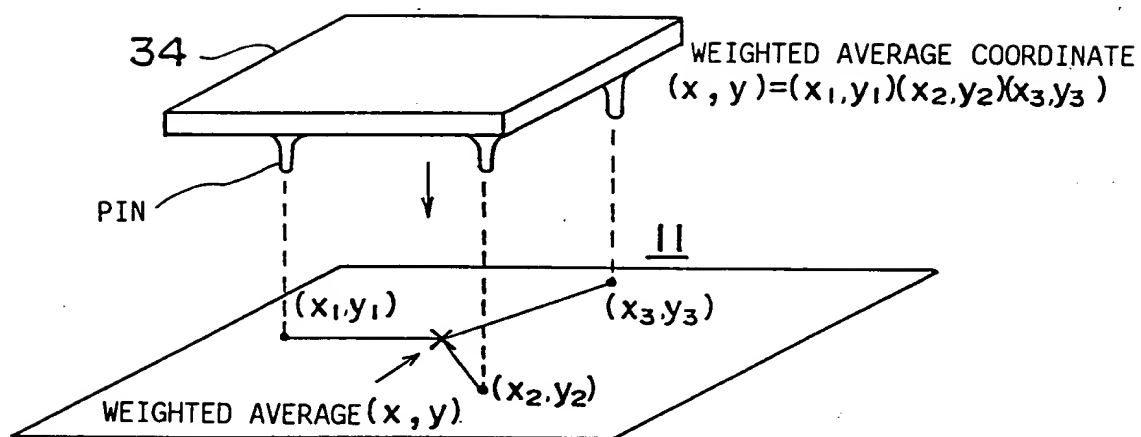


FIG. 17

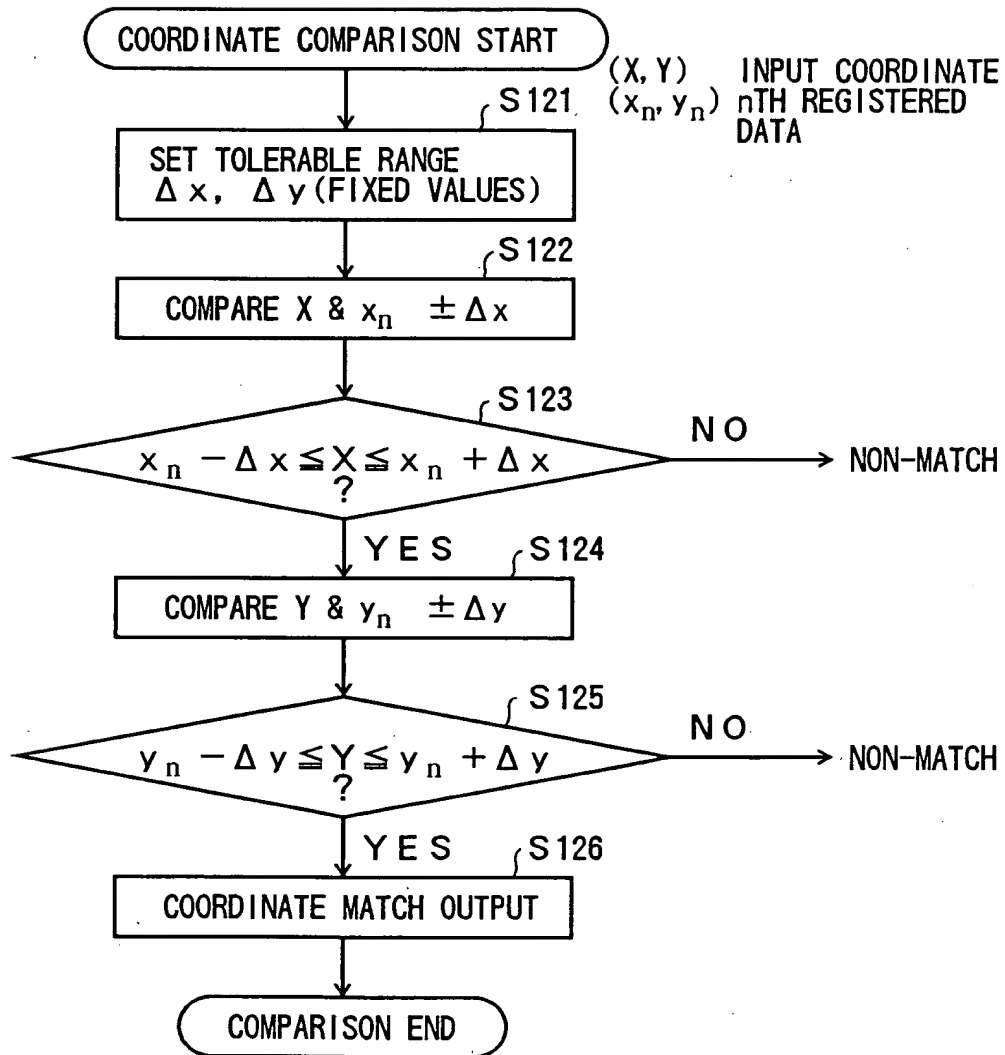


FIG. 18A

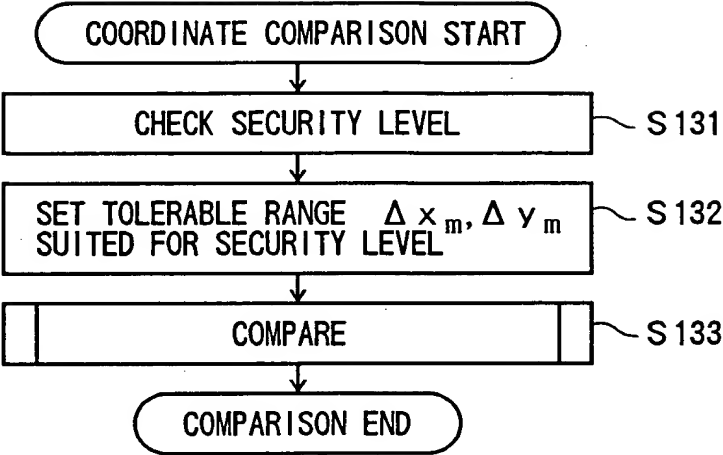


FIG. 18B

SECURITY LEVEL	TOLERABLE RANGE
1	(Δx_1 , Δy_1)
⋮	⋮
m	(Δx_m , Δy_m)
⋮	⋮
ℓ	(Δx_ℓ , Δy_ℓ)

WHERE $\Delta x_1 > \dots > \Delta x_m > \dots > \Delta x_\ell$
 $\Delta y_1 > \dots > \Delta y_m > \dots > \Delta y_\ell$

FIG. 19A

POINT NO.	CARD ORIGIN	REGISTERED DATA OF HOLE COORDINATES WITHIN CARD	COMPARISON COORDINATE RANGE
			min
1	$(x_0 \ y_0)$ TOLERABLE RANGE $(\Delta x_0, \Delta y_0)$	$(x_{01} \ y_{01})$	$(x_0 - \Delta x_0 + x_{01}, \ y_0 - \Delta y_0 + y_{01})$
2		$(x_{02} \ y_{02})$	$(x_0 - \Delta x_0 + x_{02}, \ y_0 - \Delta y_0 + y_{02})$
3		$(x_{03} \ y_{03})$	$(x_0 - \Delta x_0 + x_{03}, \ y_0 - \Delta y_0 + y_{03})$
4		$(x_{04} \ y_{04})$	$(x_0 - \Delta x_0 + x_{04}, \ y_0 - \Delta y_0 + y_{04})$

max
$(x_0 + \Delta x_0 + x_{01}, \ y_0 + \Delta y_0 + y_{01})$
$(x_0 + \Delta x_0 + x_{02}, \ y_0 + \Delta y_0 + y_{02})$
$(x_0 + \Delta x_0 + x_{03}, \ y_0 + \Delta y_0 + y_{03})$
$(x_0 + \Delta x_0 + x_{04}, \ y_0 + \Delta y_0 + y_{04})$

FIG. 19B

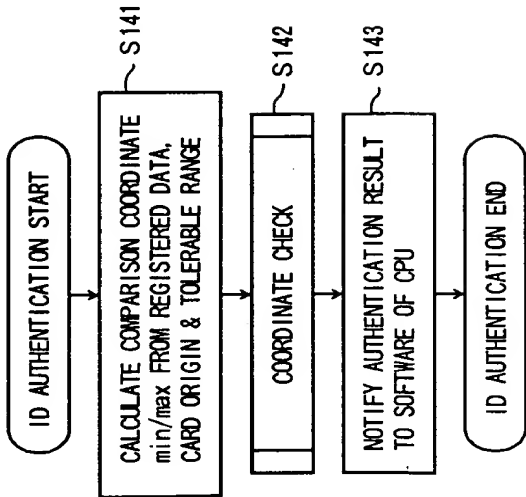


FIG. 20

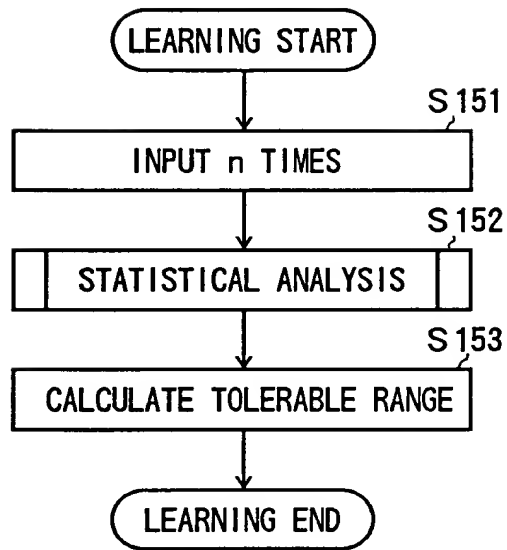


FIG. 21

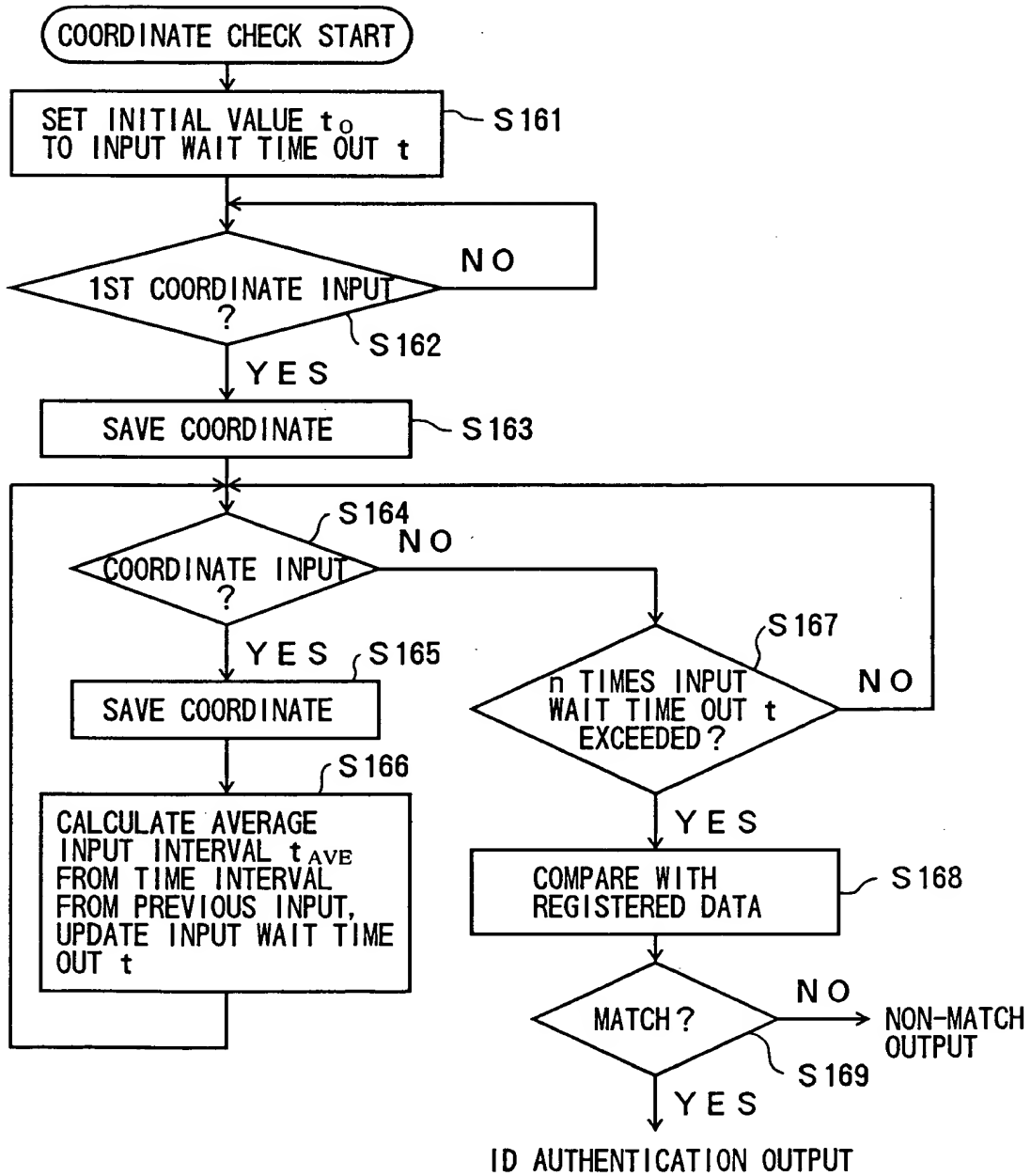


FIG. 22

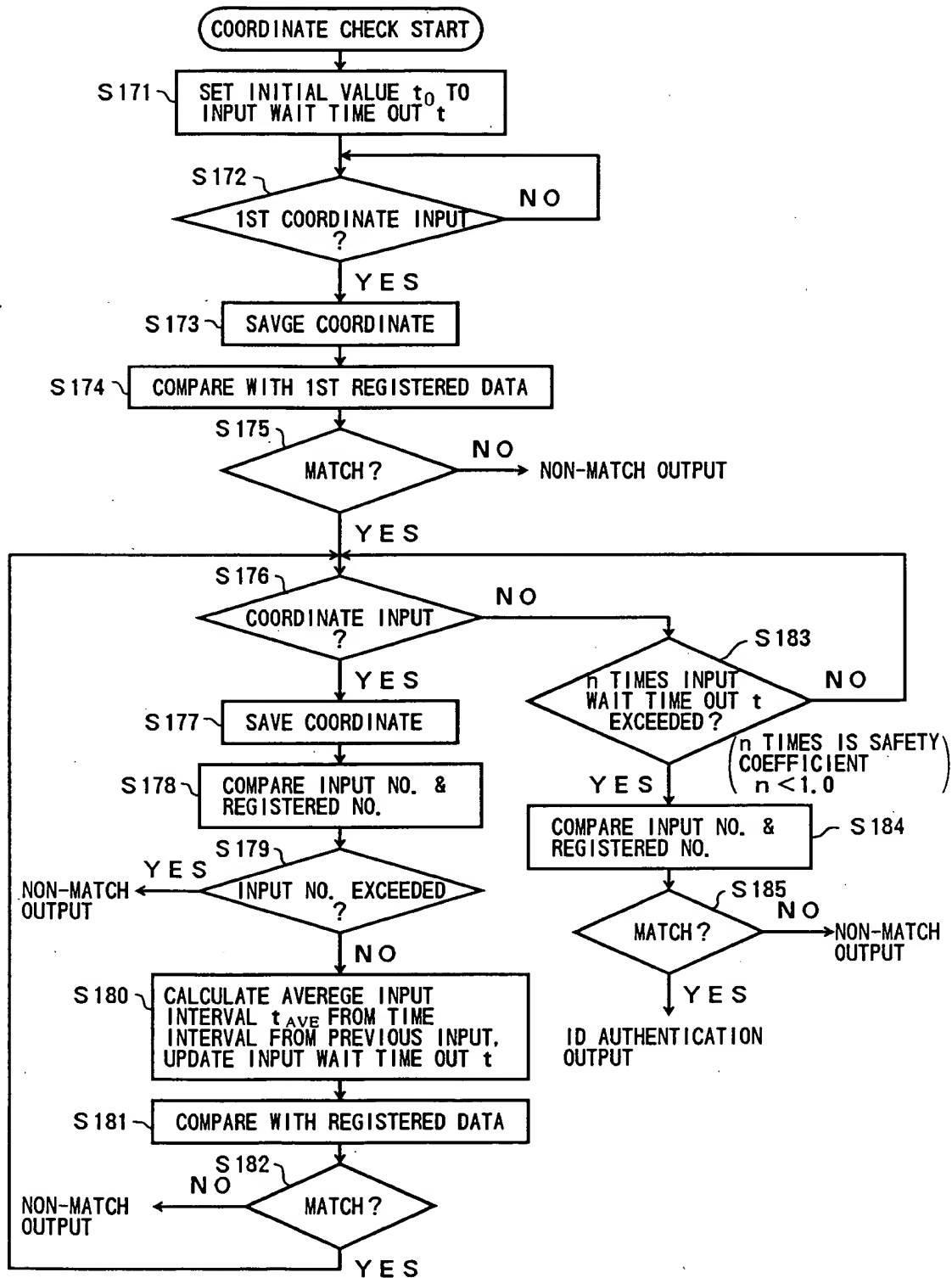


FIG. 22

FIG. 23

SOFTWARE OF CPU 1

COORDINATE DETECTING
MICROCOMPUTER 4

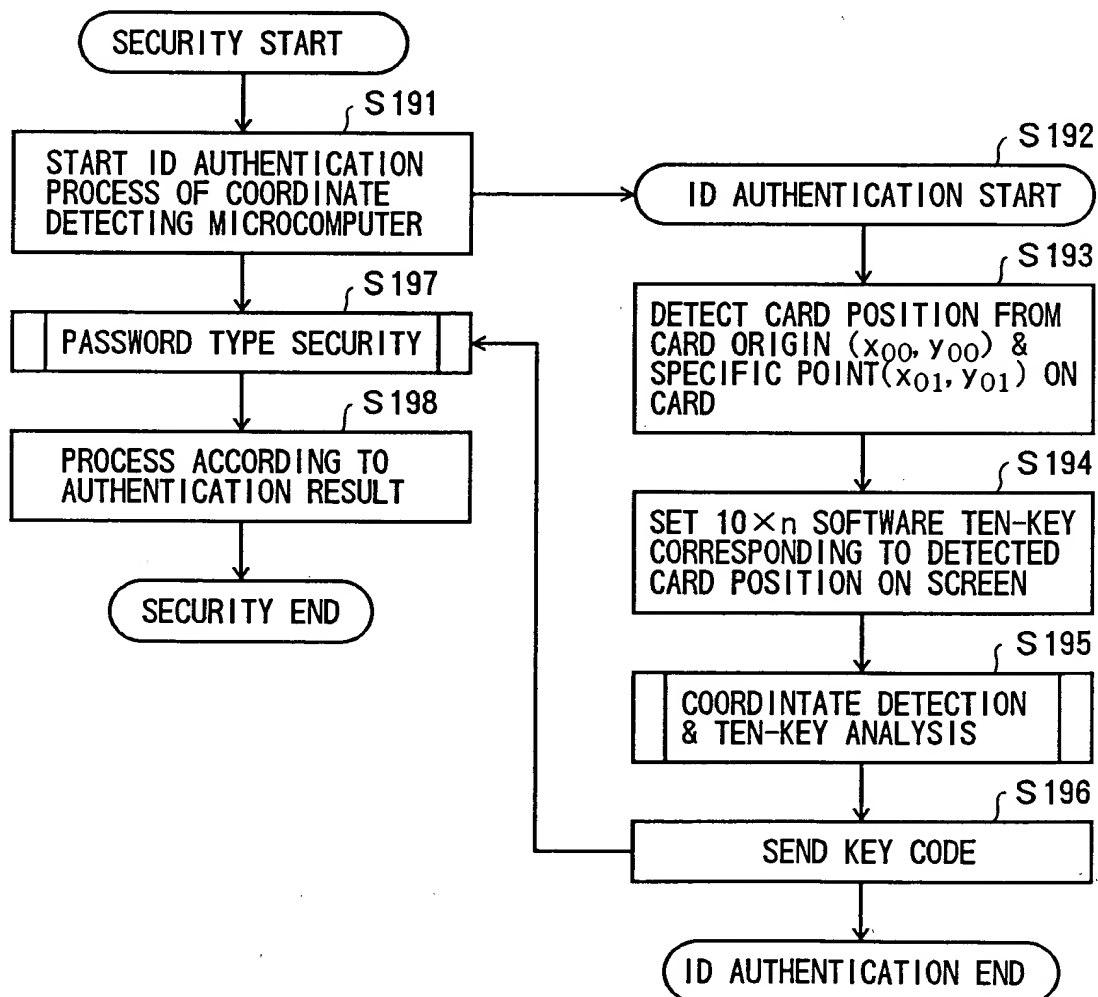


FIG. 23

21

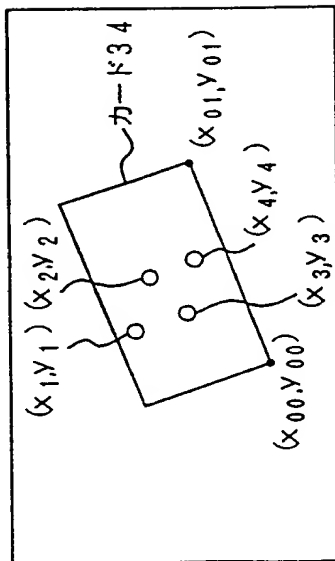


FIG. 24A

FIG. 24B

POINT DETECTED		CARD POSITION		SOFTWARE TEN-KEY		COMPARISON		NUMERICAL	
No. COORDINATE		DETECTION COORDINATE		COMPARISON COORDINATE		RESULT		VALUE	
1	(x_1, y_1)	(x_{00}, y_{00}) (x_{01}, y_{01})		(x'_1, y'_1) $= (x_{00}' x_1 \cos \Delta\theta - y_1 \sin \Delta\theta, y_{00}' x_1 \sin \Delta\theta + y_1 \cos \Delta\theta)$		(x_{12}, y_{12})		2	
2	(x_2, y_2)	$\sin \Delta\theta = \frac{y_{01} - y_{00}}{l_0}$		(x'_2, y'_2) $= (x_{00}' x_2 \cos \Delta\theta - y_2 \sin \Delta\theta, y_{00}' x_2 \sin \Delta\theta + y_2 \cos \Delta\theta)$		(x_{22}, y_{22})		6	
3	(x_3, y_3)	$\cos \Delta\theta = \frac{x_{01} - x_{00}}{l_0}$		(x'_3, y'_3) $= (x_{00}' x_3 \cos \Delta\theta - y_3 \sin \Delta\theta, y_{00}' x_3 \sin \Delta\theta + y_3 \cos \Delta\theta)$		(x_{32}, y_{32})		9	
4	(x_4, y_4)	l_0 : DISTANCE BETWEEN POSITIONING HOLES		(x'_4, y'_4) $= (x_{00}' x_4 \cos \Delta\theta - y_4 \sin \Delta\theta, y_{00}' x_4 \sin \Delta\theta + y_4 \cos \Delta\theta)$		(x_{42}, y_{42})		2	

FIG. 25

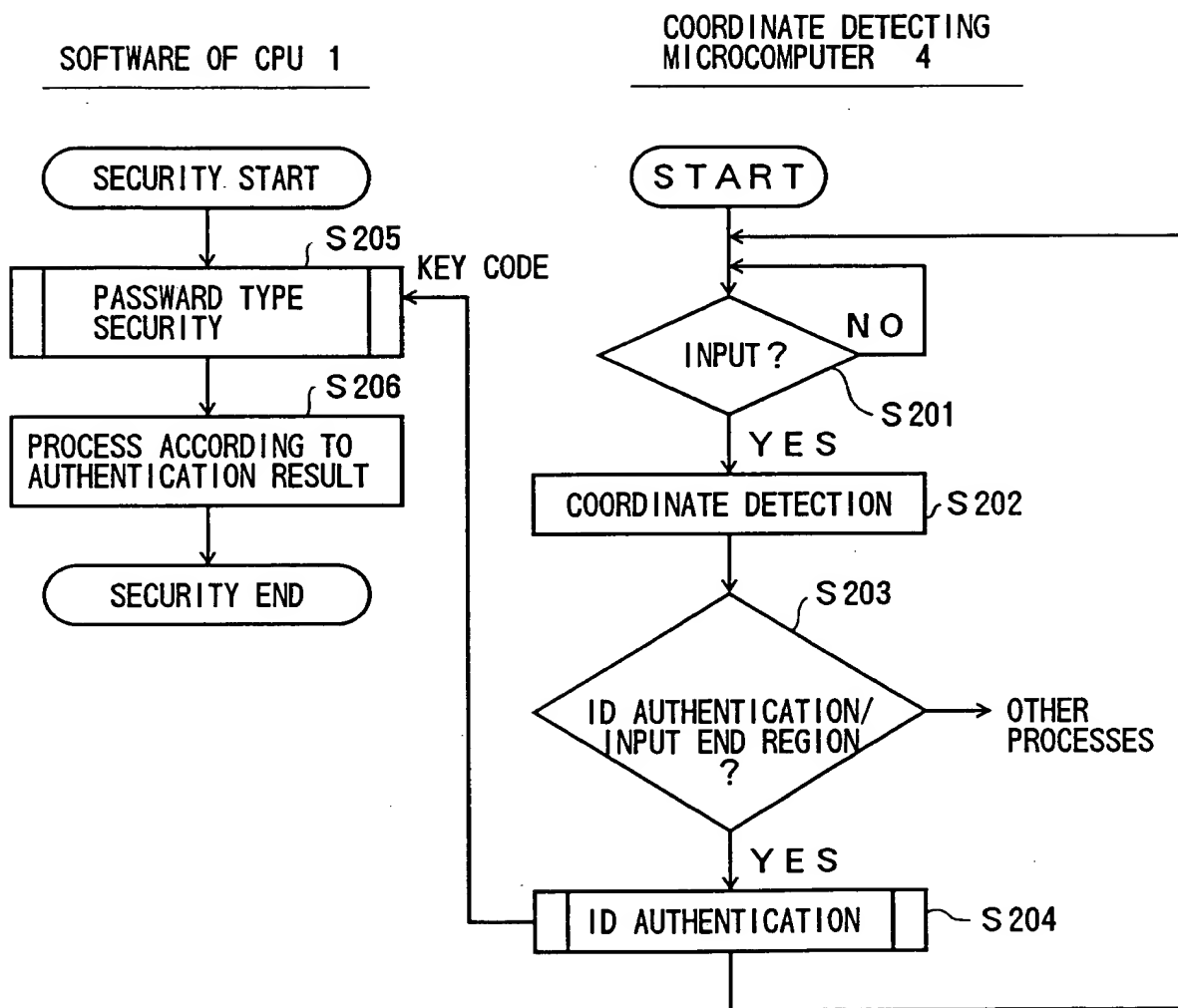


FIG. 26

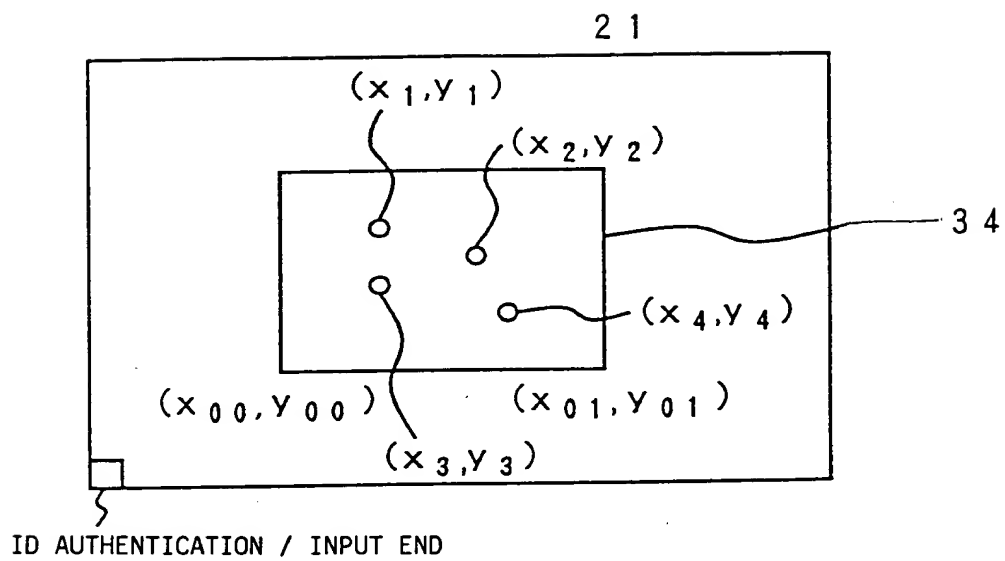


FIG. 27

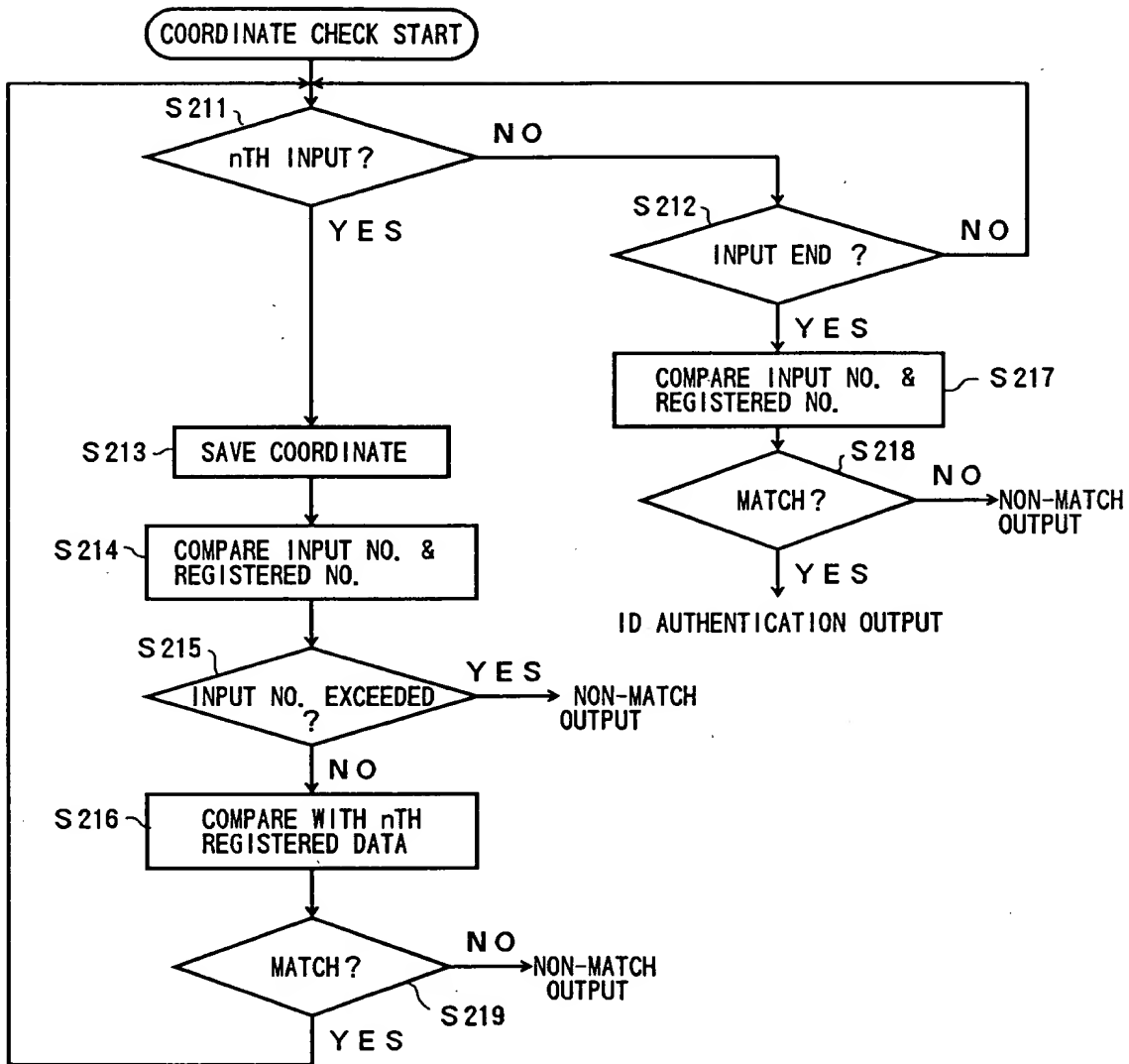


FIG. 28

POINT DETECTED NO. COORDINATE		CARD POSITION DETECTION COORDINATE	COMPARISON COORDINATE	REGISTERED COORDINATE	OUTPUT KEY CODE AFTER ID AUTHENTICATION
1	(x ₁ y ₁)	(x ₀₀ y ₀₀) (x ₀₁ y ₀₁) $\sin \Delta \theta = \frac{y_{01} - y_{00}}{\ell_0}$	(x ₀₀ + x ₁ cos Δ θ - y ₁ sin Δ θ, y ₀₀ + x ₁ sin Δ θ + y ₁ cos Δ θ)	(x ₁ , y ₁)	2
2	(x ₂ y ₂)	$\cos \Delta \theta = \frac{y_{01} - y_{00}}{\ell_0}$	(x ₀₀ + x ₂ cos Δ θ - y ₂ sin Δ θ, y ₀₀ + x ₂ sin Δ θ + y ₂ cos Δ θ)	(x ₂ , y ₂)	6
3	(x ₃ y ₃)	$\sin \Delta \theta = \frac{y_{01} - y_{00}}{\ell_0}$	(x ₀₀ + x ₃ cos Δ θ - y ₃ sin Δ θ, y ₀₀ + x ₃ sin Δ θ + y ₃ cos Δ θ)	(x ₃ , y ₃)	9
4	(x ₄ y ₄)	ℓ ₀ : DISTANCE BETWEEN POSITIONING HOLES	(x ₀₀ + x ₄ cos Δ θ - y ₄ sin Δ θ, y ₀₀ + x ₄ sin Δ θ + y ₄ cos Δ θ)	(x ₄ , y ₄)	2

FIG. 29

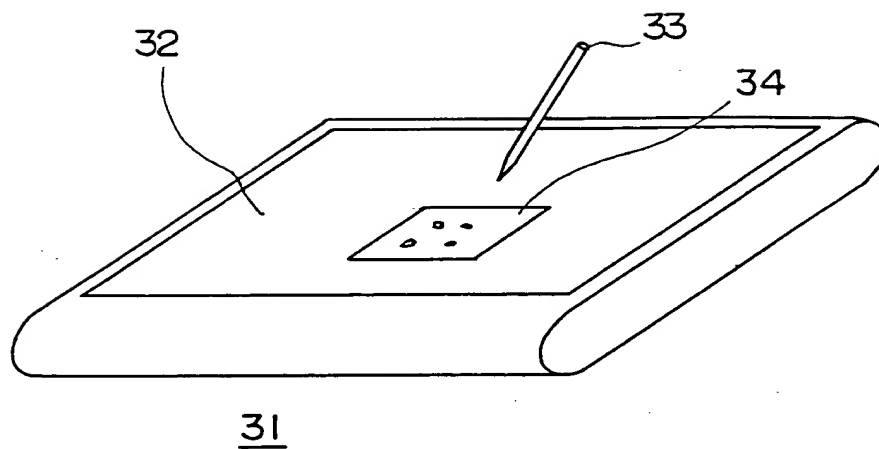


FIG. 30

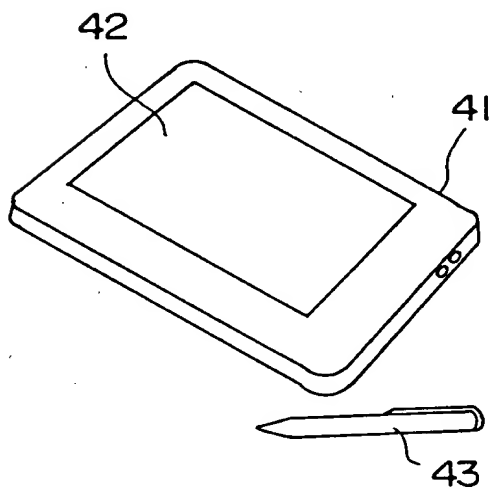


FIG. 31

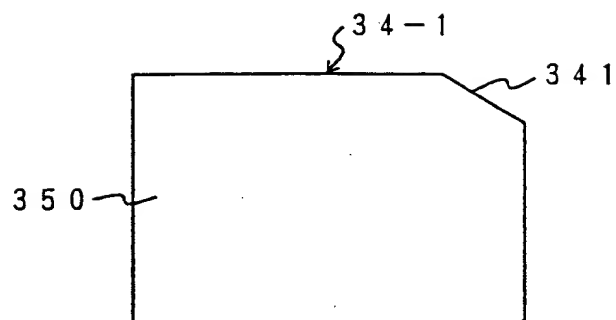


FIG. 32A

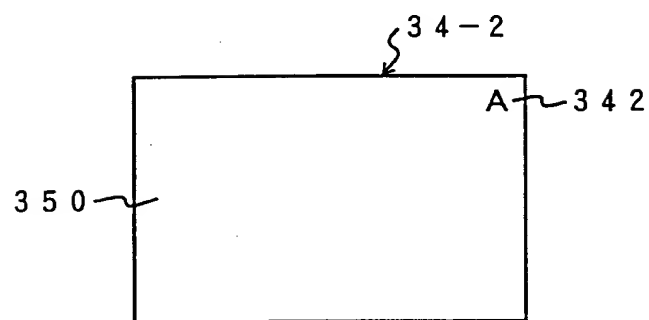


FIG. 32B

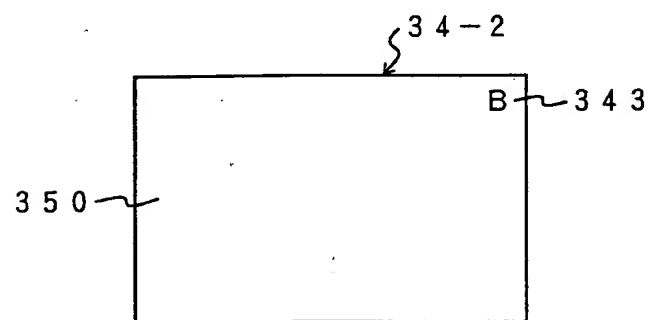


FIG. 33

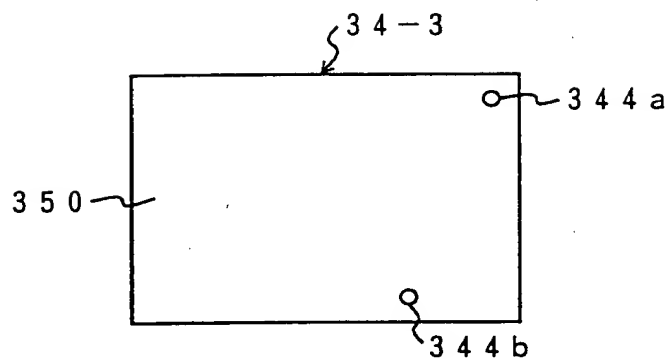


FIG. 34

